

Synergies between solar and night-time AO

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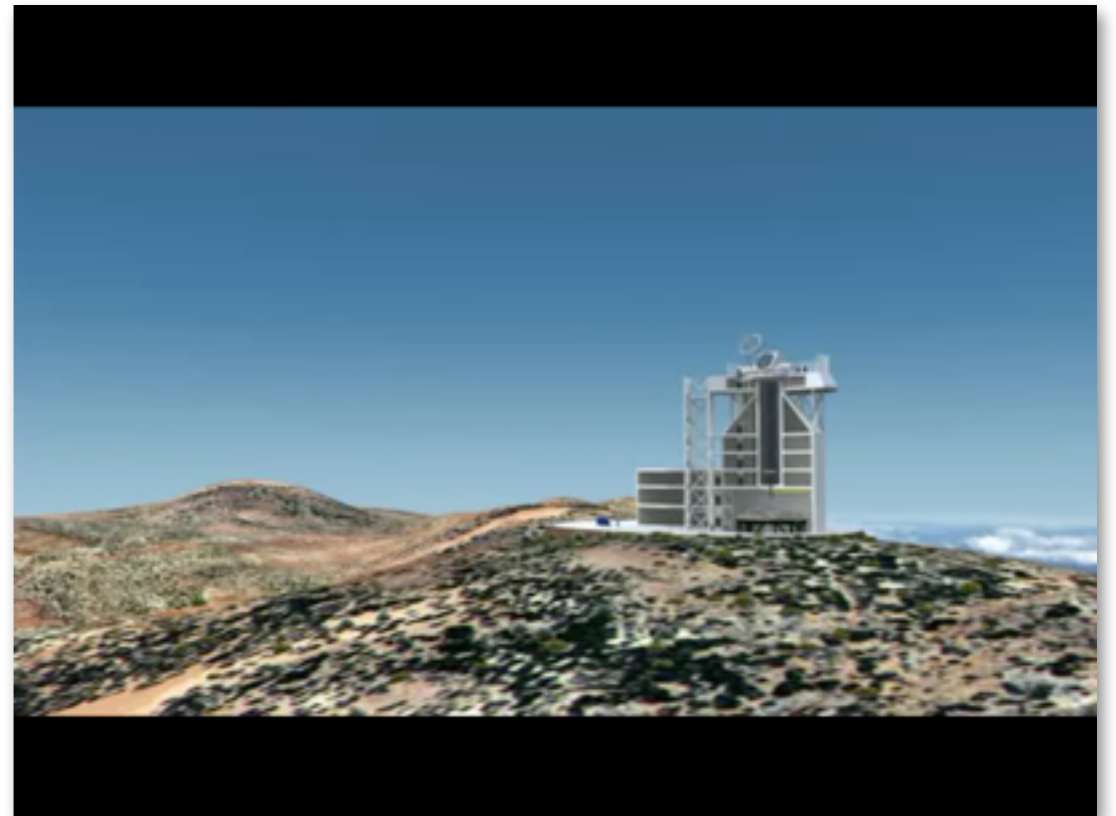
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European Solar Telescope

EST is a pan-European project involving 29 partners from 15 countries

One month ago, EST entered the ***ESFRI 2016*** EU roadmap



Design Study EU Grant Agreement 212482

FP7, Grant Agreement 312495 

H2020-INFRADEV-1-2014-1 



- EST is a 4-meter class telescope optimized for high precision polarimetric measurements in the solar atmosphere



- It will be equipped with a **polarization-free** MCAO system, this is of paramount importance to achieve the required **10^{-5}** polarimetric sensitivity (same order of magnitude of the required sensitivity for polarimetric observations of exoplanets in reflected light)
- Need to resolve the small scale magnetic fields in the solar photosphere (30 km)

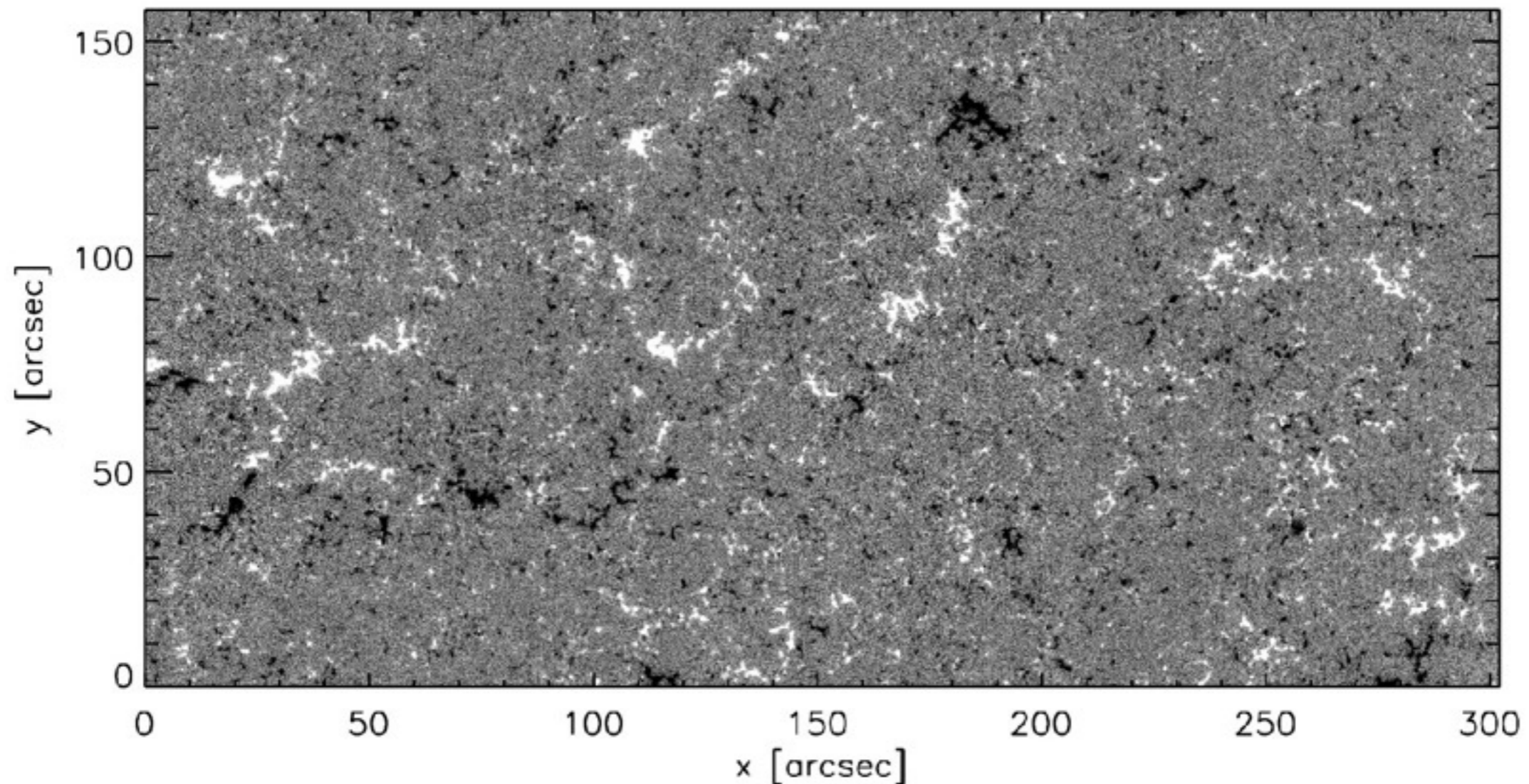
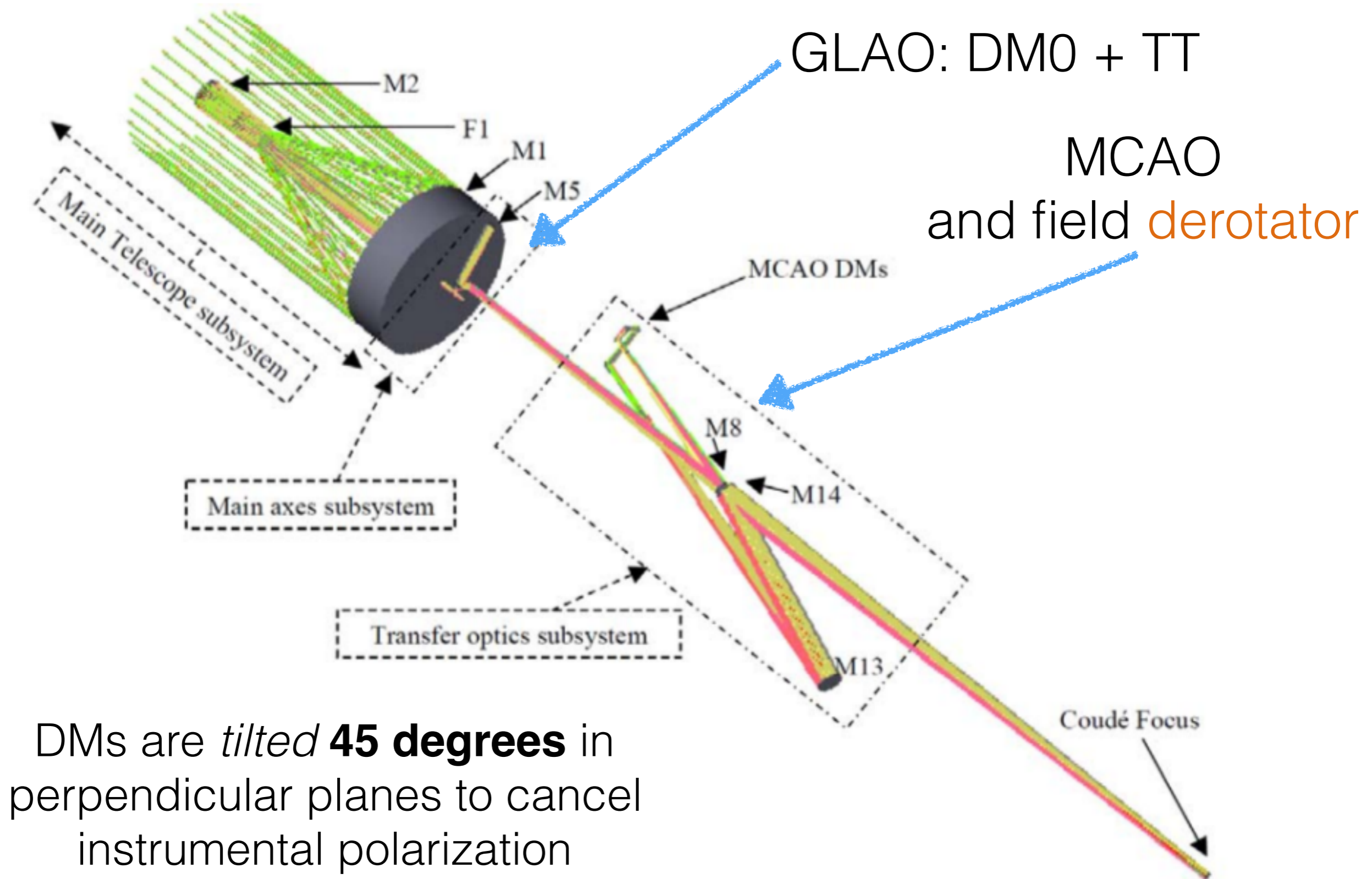


Image from HINODE/SOT-SP


Polarization-free MCAO



Tilted DMs: drawbacks

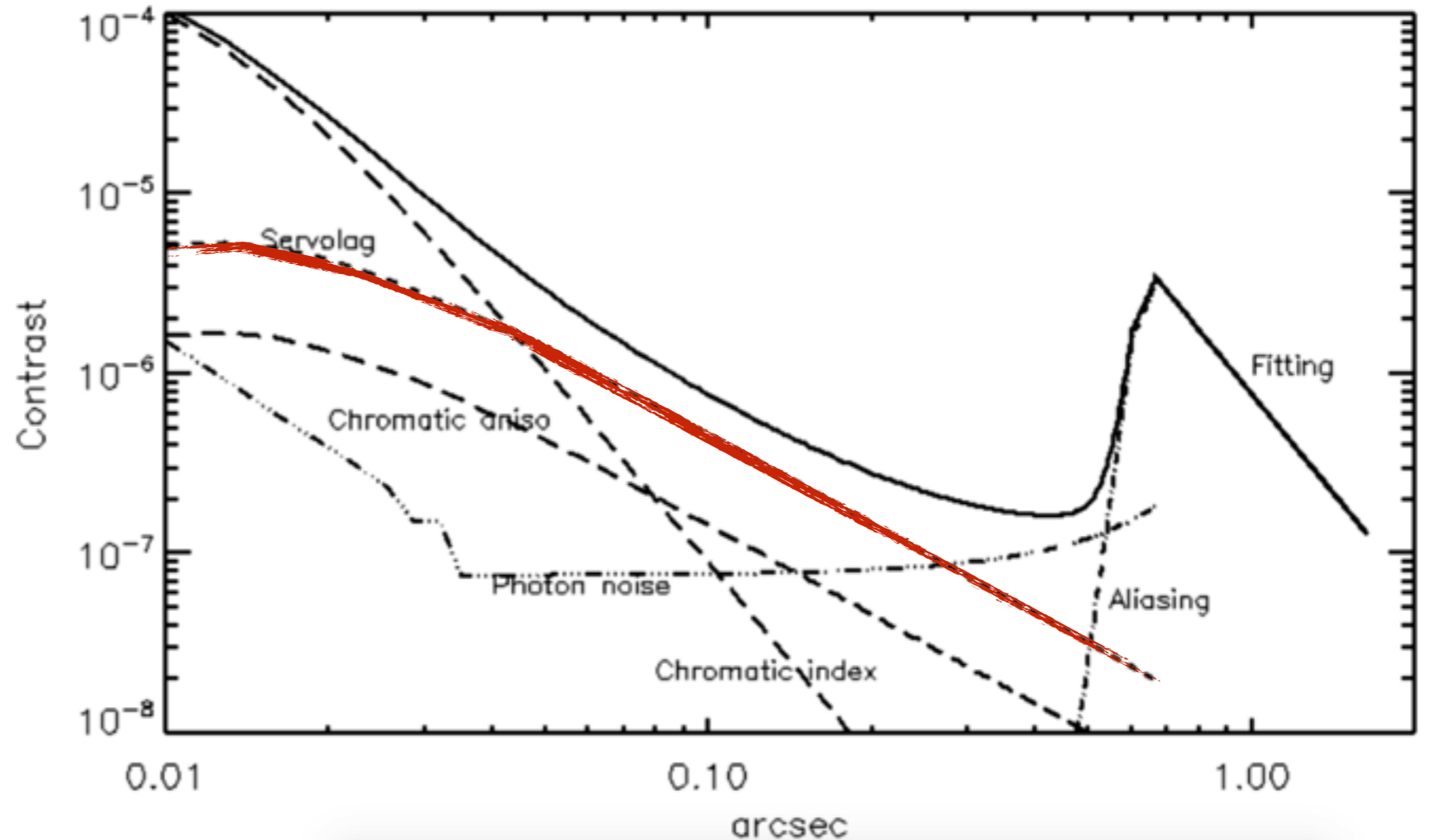
- **Non-standard configuration** for the DMs:
 - **Elliptic pupils**
 - **Conjugation** height dependent on the position on the DM
 - Sensitivity to **misalignments** due to the rotation between the pupil and the MCAO DMs
- Different **spacing** of the projected pitch on the entrance pupil

Solar AO peculiarities

- Polarimetric constraints: high sensitivity & accuracy + small instrumental polarization →  GREST
- Lack of AO tracking points for both disk (quiet Sun) and limb observations
- Time lag → low contrast and extended target

Five error sources in AO systems

- Fitting error
- WFS aliasing error
- **Servo-lag**
- WFS noise
- Anisoplanatism



Kasper et al. 2012

Servo lag represents one of the most severe limitations in AO systems

Predictive control

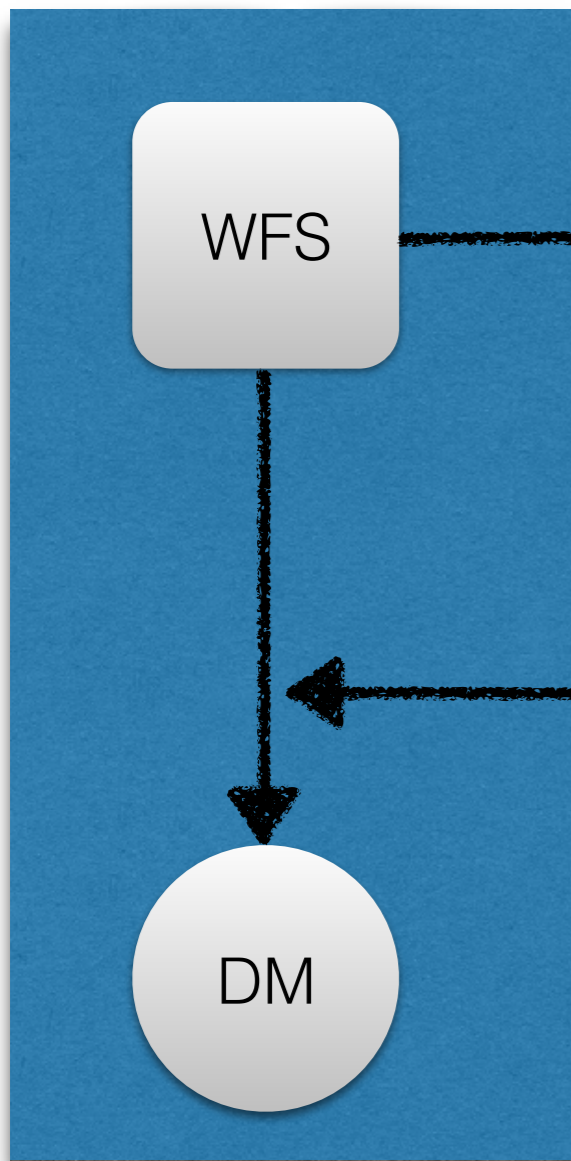
- A process can be predicted if:
 - is stationary
 - its future evolution depends of its **past** states
- The turbulence is **predictable** (frozen) over a short time (a few ms, see Dessenne et al 1998, Jorgenson & Aitken 1992, Jackson et al. 2015, Tesch 2015)

Predictive control with **Fors** Closed Loop Forecasting System

- We have developed a predictive control software module based upon ARMA (**A**uto**R**egressive **M**oving **A**verage) processes
- If a process is **stationary** then there will be **AT LEAST** one ARMA(p,q) statistical process describing it

$$B(X_{n+1}) = \phi_1 X_n + \dots + \phi_p X_{n+1-p} + \sum_{j=1}^n \theta_{nj} [X_{n+1-j} - B(X_{n+1-j})] \quad \text{if } n > m.$$

Coefficients of the ARMA process. The future evolution at time $n+1$ can be written as a **combination of the past states** of the process



$$B(X_{n+1}) = \phi_1 X_n + \dots + \phi_p X_{n+1-p} + \sum_{j=1}^n \theta_{nj} [X_{n+1-j} - B(X_{n+1-j})] \quad \text{if } n > m.$$

Learning layer

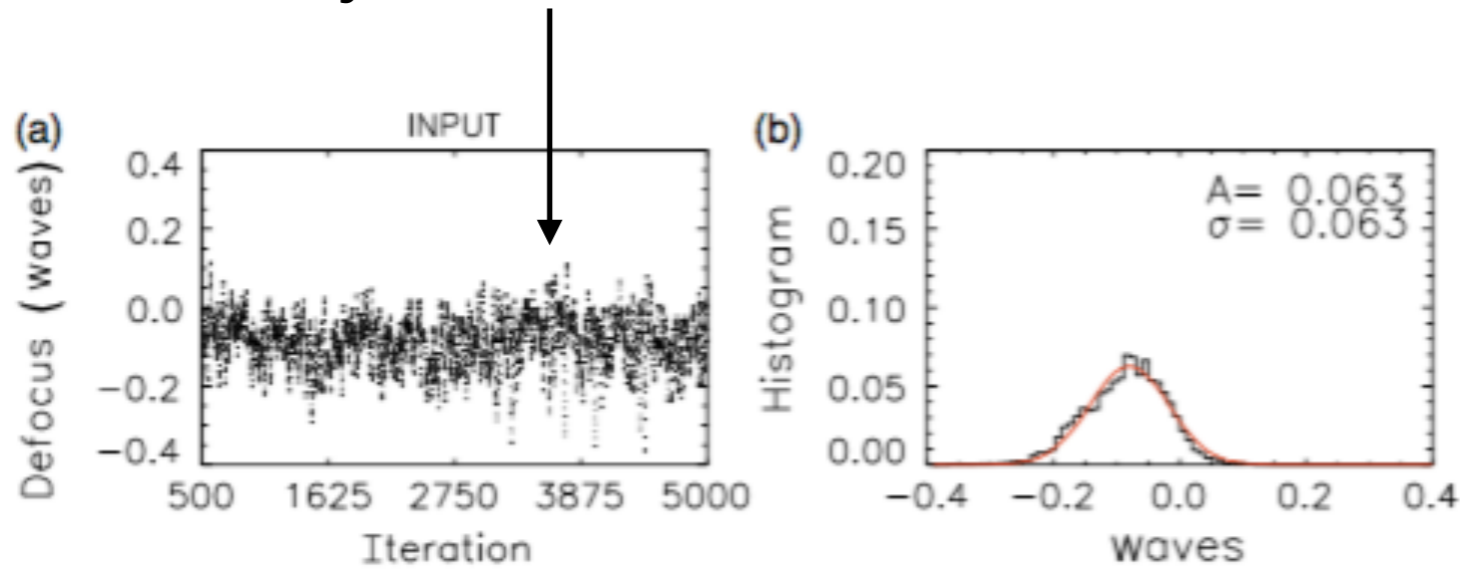
DM commands are modified to drive the mirror ahead of time and follow the short time evolution of the process

○ Parallel (offline) learning/modeling

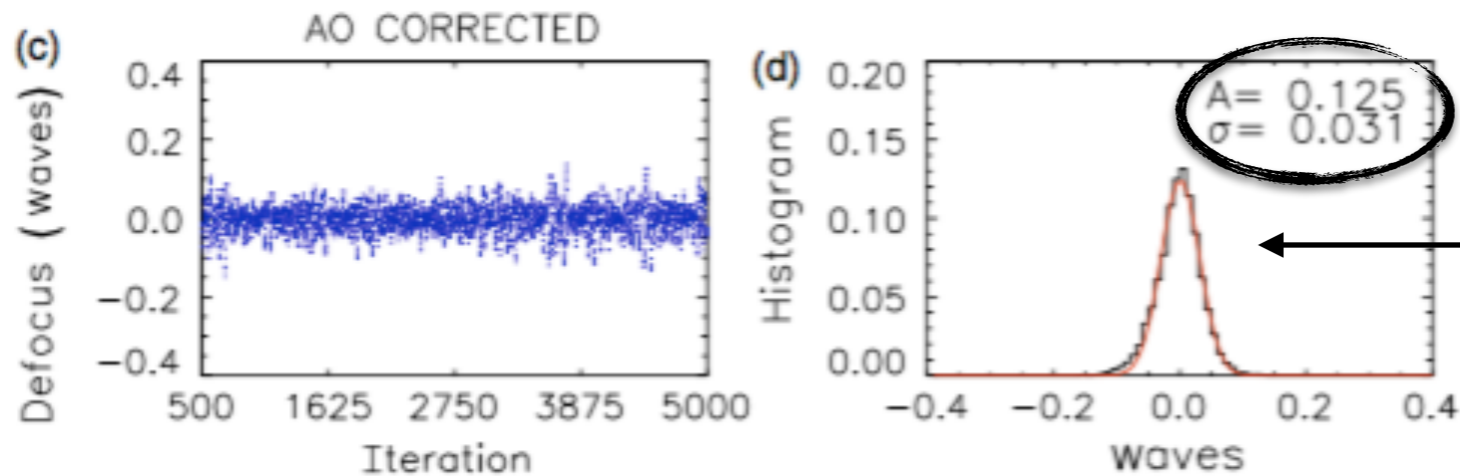


○ Periodic update of the ARMA coefficients

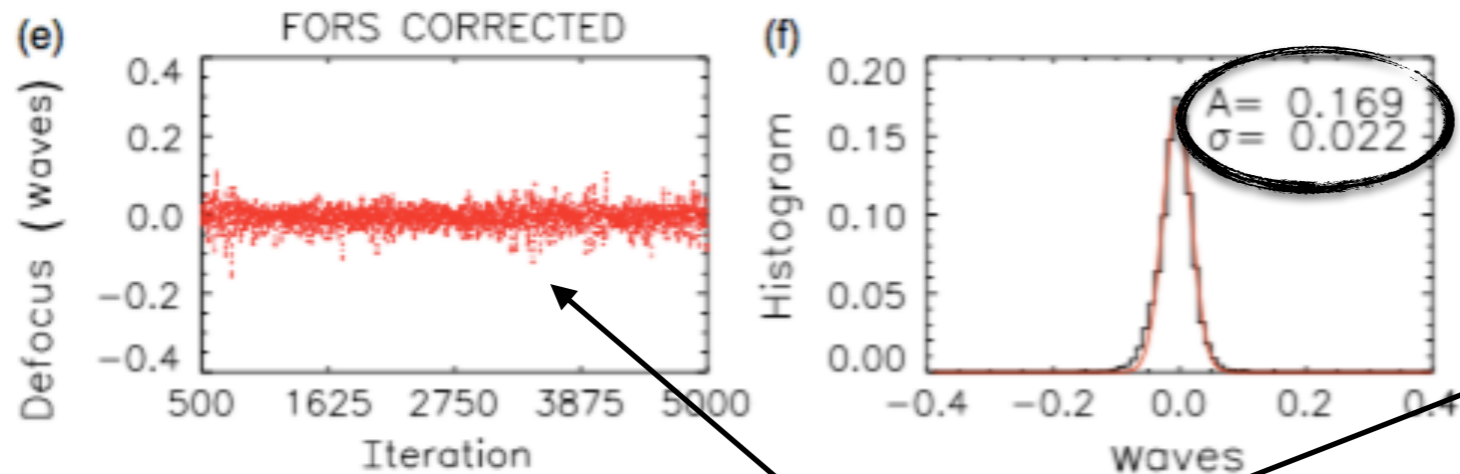
Real on-sky recorded aberrations



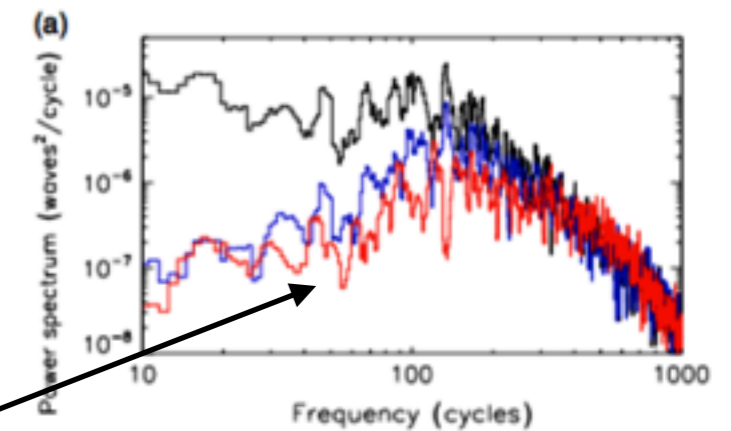
Reduction of the residual aberrations up to 30%



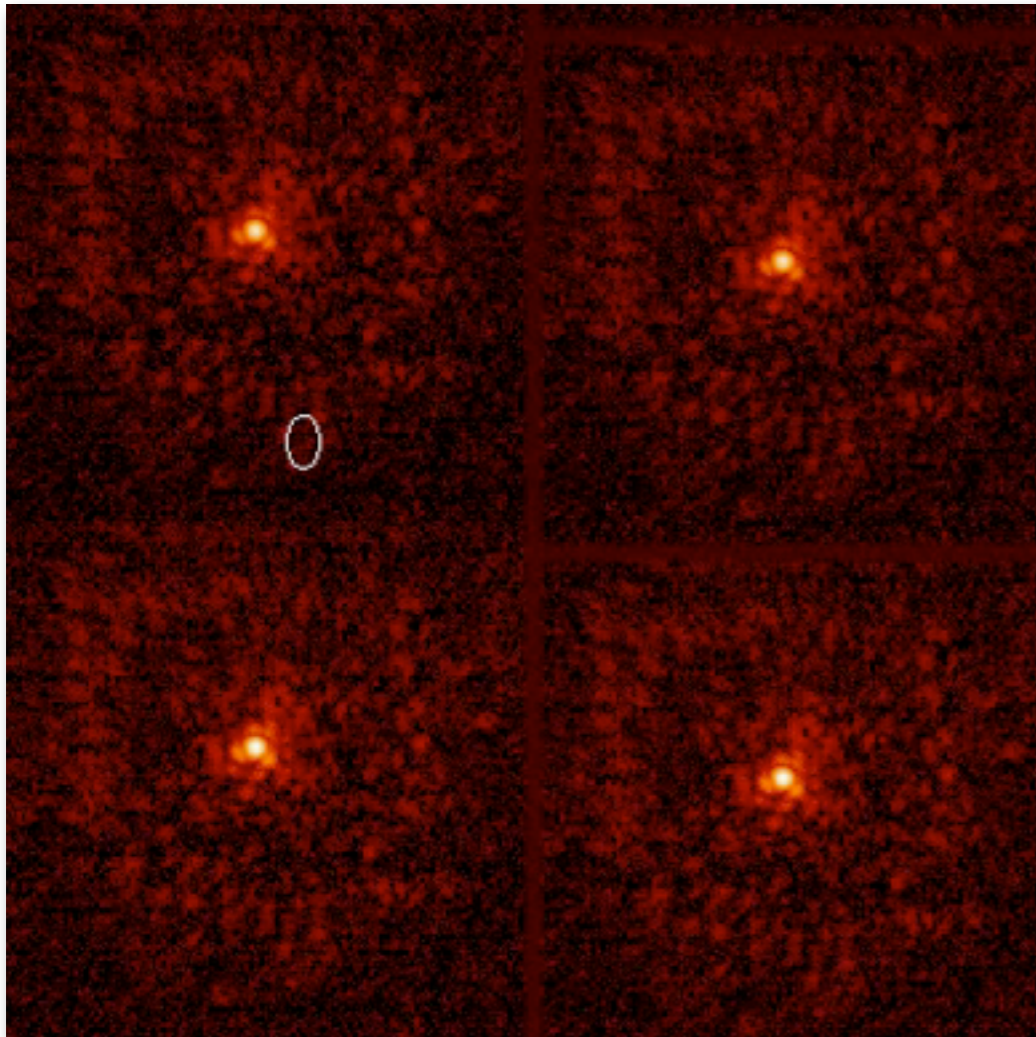
Without prediction



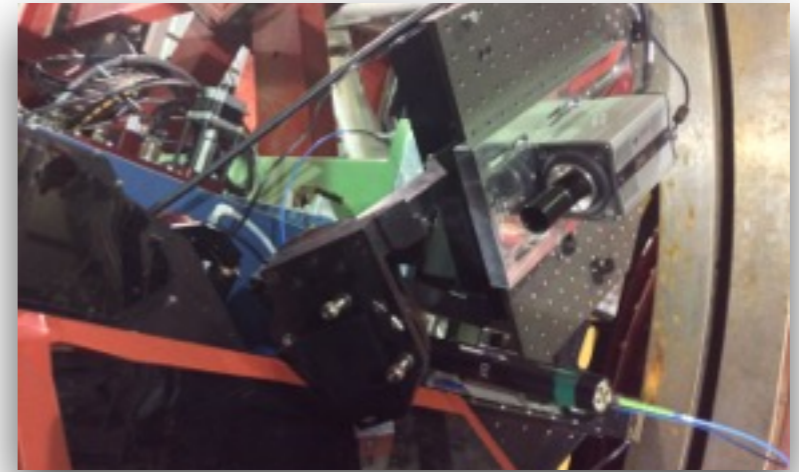
Predictive control



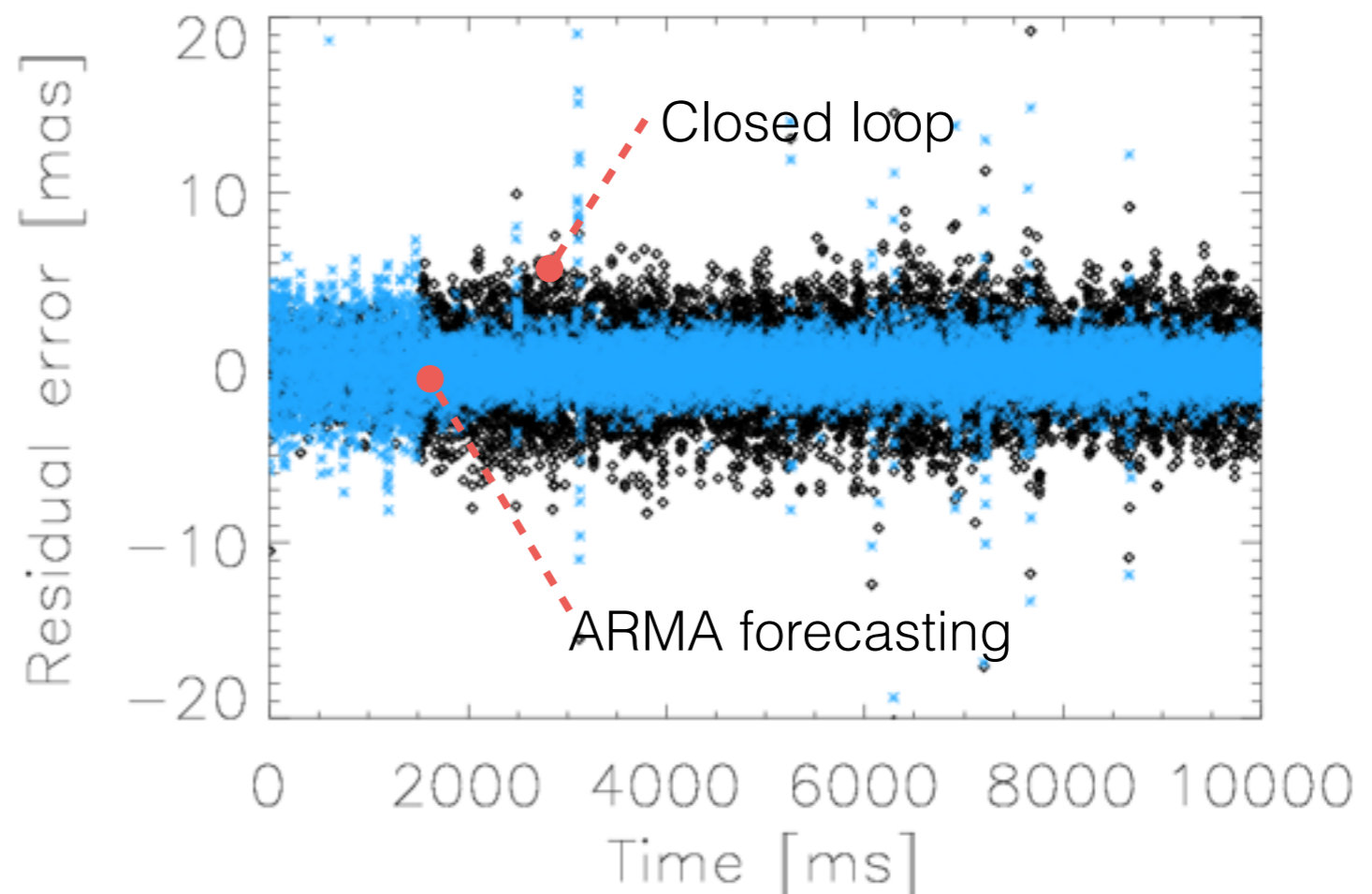
Testing ARMA on LBT-SHARK residual vibrations



Using real on-sky LBT-SHARK data (1 ms cadence), we have simulated the performances of the ARMA forecasting reducing residual vibrations



$\sigma = 2.6 \text{ mas}$ \rightarrow $\sigma_{ARMA} = 1.5 \text{ mas}$



ARMA forecasting: from solar to night-time AO

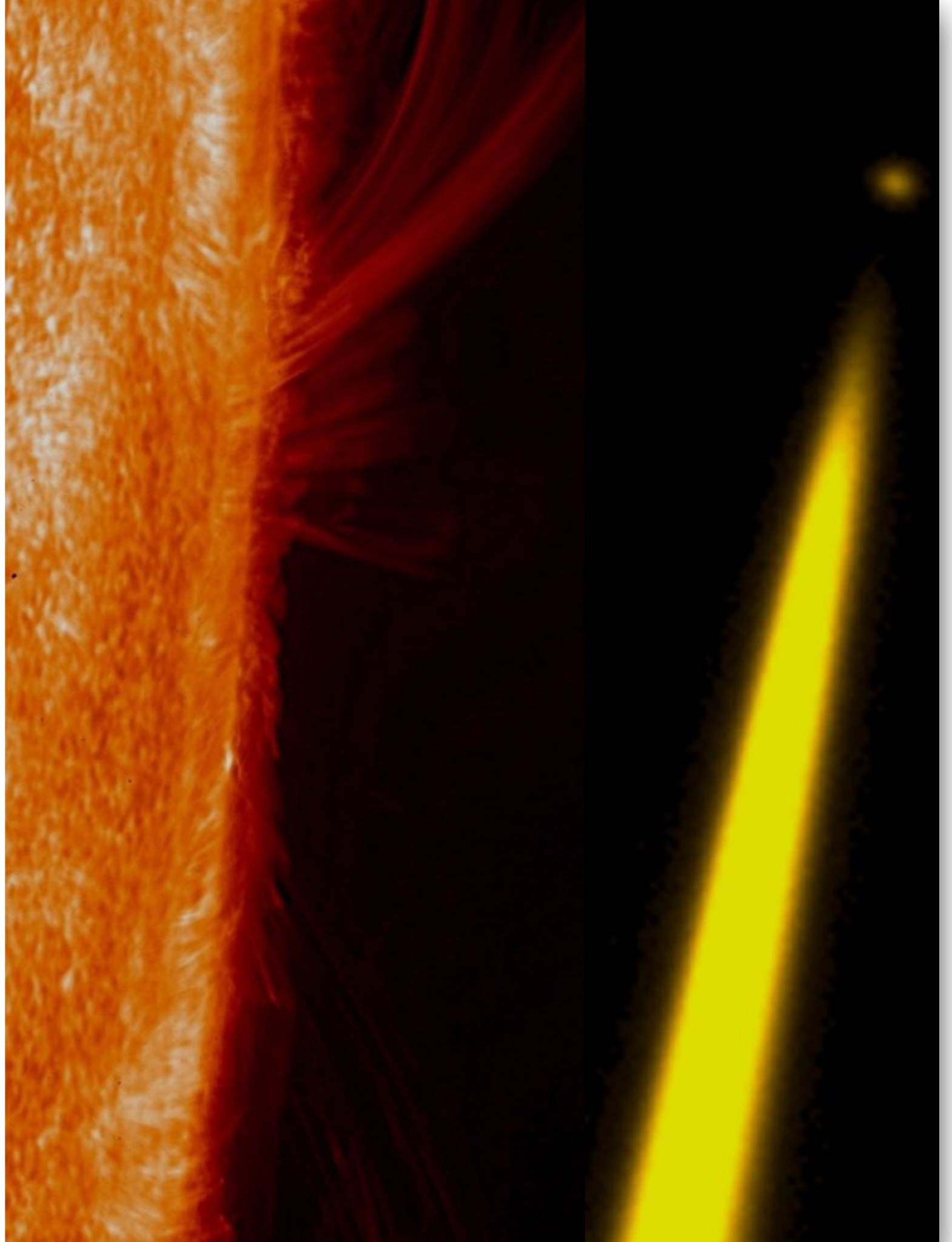
- Our contribution to ELT-MOSAIC



- Ongoing integration into DARC, the real-time control system of CANARY@WHT

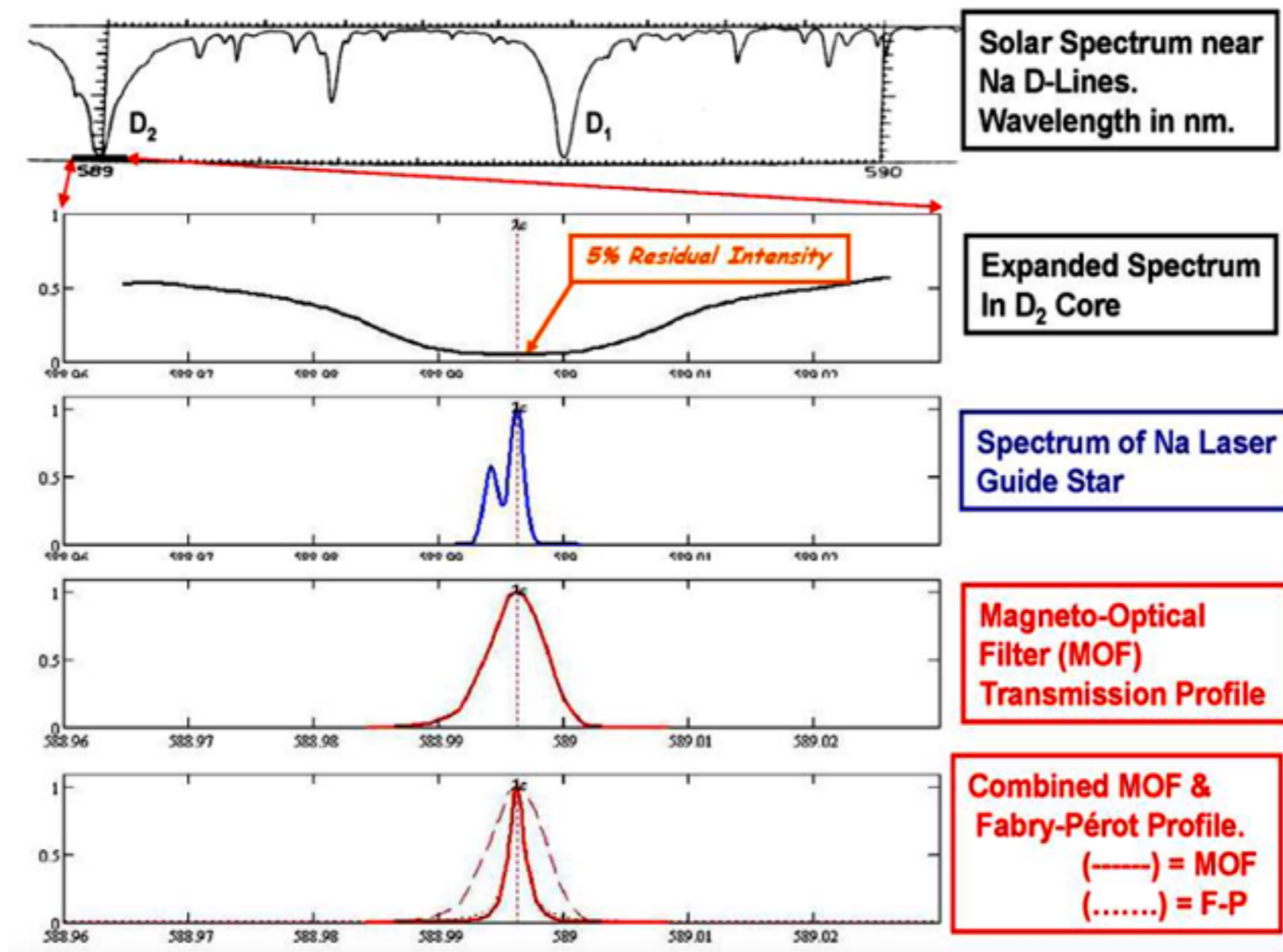
DARC

LGS in daytime?



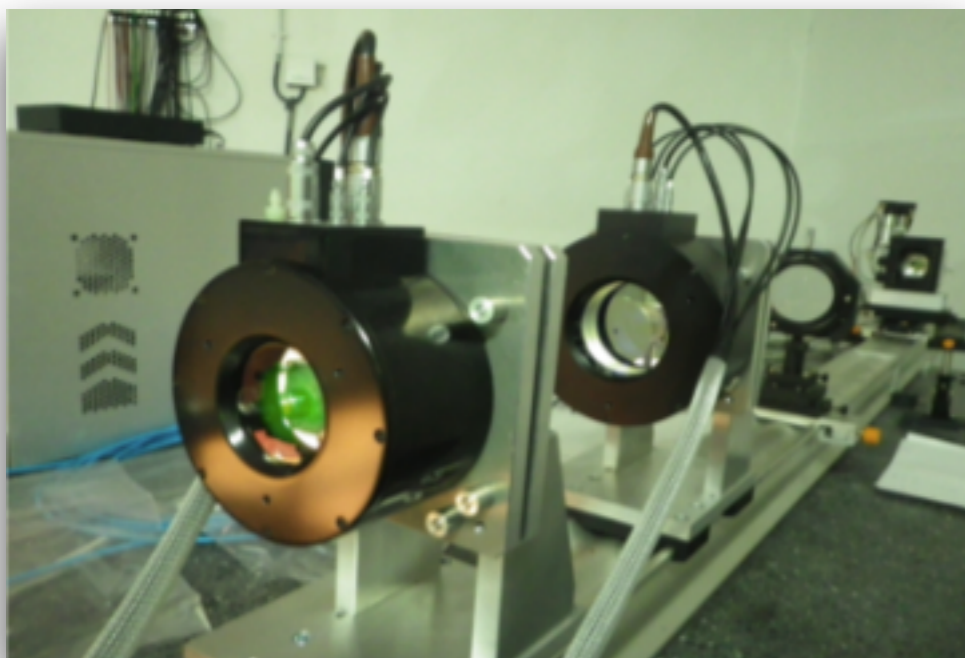
Suppressing the sky background

- The feasibility of LGS in daytime was demonstrated by Beckers (2008). This is strategic for both solar and thermal IR observations





Baseline 190 m:
large spot elongation



Receiver: *HELLRIDE@VTT* a dual Fabry-Perot 2D spectrograph

- Extrafocal positioning
- 200 x 200 arcsec FoV
- 25 mÅ bandpass
- Tunable wavelength